

#### GENERAL INFORMATION

The A/RH Duct Series Sensor is a Relative Humidity transmitter that can be powered with either an AC or DC supply voltage. The RH Duct transmitter is field selectable with a 4-20 mA, 0-5 VDC, or 0-10 VDC output signal that is equivalent to 0 to 100% RH. This sensor is designed for use with electronic controllers in commercial heating and cooling building management systems. All units are shipped from the factory set up for a 4-20 mA output. The transmitter can also include an optional temperature sensor for monitoring the space temperature.

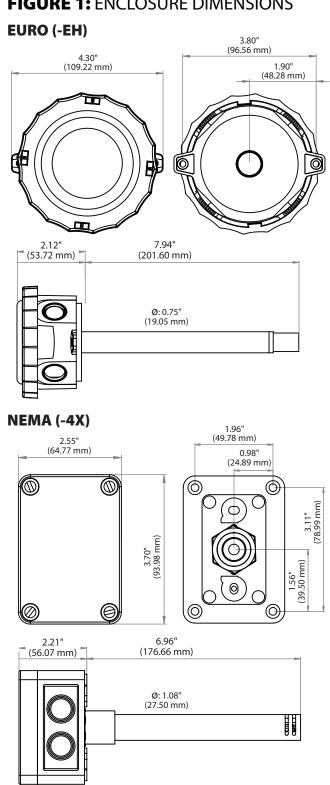
#### For optimal readings, follow these tips:

- The sensor should be mounted in the middle of the duct where air circulation is well mixed (no stratification), and not blocked by obstructions. Stratification and obstructions can cause sensing errors. An example is downstream from a heating or cooling coil.
- Duct probe should be placed (3) to (4) duct segments down from any bend or obstructions and away from 90° bends.
- Mount the sensor on the top or sides of duct work; mounting on the bottom risks damage due to moisture.

#### **MOUNTING INSTRUCTIONS**

The Euro enclosure (-EH) requires a 0.875" (22.23 mm) hole in the duct, and the Nema 4X enclosure (-4X) requires a 1.25" (31.75 mm) hole - see FIGURE 1. After drilling, insert the probe through the hole until the foam pad is tight to the duct. Drill pilot holes for the mounting screws. Use the enclosure as a guide, or use the dimensions listed on the right to measure out.

Now fasten and insert mounting screws through the mounting holes and tighten until the unit is held firmly to the duct. Refer to Wiring Instructions (p. 2-4) to make necessary connections.



# FIGURE 1: ENCLOSURE DIMENSIONS



# FIGURE 2: TEMPERATURE WIRING NEMA (-4X) TEMPERATURE WIRE LEADS TEMPERATURE URE (-EH) TEMPERATURE WIRE LEADS

## WIRING INSTRUCTIONS

#### PRECAUTIONS

- Do not run the temperature sensor wiring in any conduit with line voltage (24/120/230 VAC) if utilizing resistance temperature signal.
- Remove power before wiring. Never connect or disconnect wiring with power applied.
- When using a shielded cable, ground the shield only at the controller end. Grounding both ends can cause a ground loop.
- It is recommended you use an isolated UL-listed class 2 transformer when powering the unit with 24 VAC. Failure to wire the devices with the correct

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FIGURE 3: MOUNTING DIMENSIONS

- polarity when sharing transformers may result in damage to any device powered by the shared transformer.
- If the 24 VDC or 24VAC power is shared with devices that have coils such as relays, solenoids, or other inductors, each coil must have an MOV, DC/AC Transorb, Transient Voltage Suppressor (ACI Part: 142583), or diode placed across the coil or inductor. The cathode, or banded side of the DC Transorb or diode, connects to the positive side of the power supply. Without these snubbers, coils produce very large voltage spikes when de-energizing that can cause malfunction or destruction of electronic circuits.

#### **RELATIVE HUMIDITY WIRING INSTRUCTIONS**

Open the cover of the enclosure. ACI recommends 16 to 26 AWG twisted pair wires or shielded cable for all transmitters. Twisted pair may be used for 2-wire current output transmitters or 3-wire for voltage output. Refer to **FIGURE 5** (p. 3) for wiring diagrams.

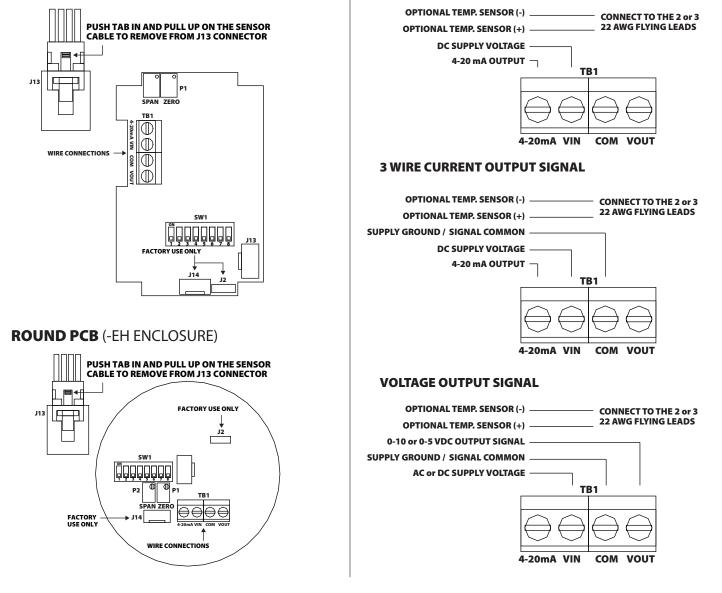
#### **TEMPERATURE WIRING INSTRUCTIONS**

ACI recommends 16 to 26 AWG twisted pair wires or shielded cable for all temperature sensors. ACI recommends a separate cable be pulled for Temperature signal only. Temperature Signal wiring must be run separate from low and high voltage wires (24/120/230VAC). All ACI thermistors and RTD temperature sensors are both non-polarity and non-position sensitive. All thermistor type units are supplied with (2) flying lead wires, and all RTD's are supplied with (2) or (3) flying lead wires – see **FIGURE 6** (p. 3). The number of wires needed depends on the application. Connect thermistor/RTD wire leads to controller analog input wires using wire nuts, terminal blocks, or crimp style connectors. All wiring must comply with local and National Electric Codes. After wiring, attach the cover to the enclosure.



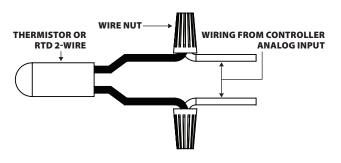
## FIGURE 4: PRINTED CIRCUIT BOARD

#### SQUARE PCB (-4X ENCLOSURE)



# FIGURE 6: TEMPERATURE WIRING

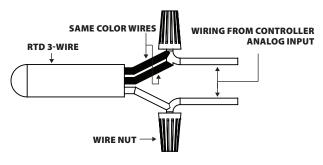




#### **3-WIRE RTD WIRING**

FIGURE 5: OUTPUT SIGNALS

**2 WIRE CURRENT OUTPUT SIGNAL** 



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#### WIRING INSTRUCTIONS (Continued) TEMPERATURE WIRING INSTRUCTIONS (Continued)

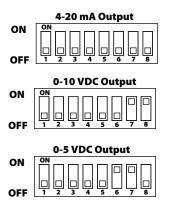
**Note:** When using a shielded cable, be sure to connect only (1) end of the shield to ground at the controller. Connecting both ends of the shield to ground may cause a ground loop. When removing the shield from the sensor end, make sure to properly trim the shield to prevent any chance of shorting.

**Note:** If the controller requires a (2) wire input for a RTD, connect the (2) common wires (same color) together. If the controller requires (3) wires, use (3) individual wires - see **FIGURE 6** (p. 3).

## **OUTPUT SIGNALS**

Switches 6, 7, and 8 are used to set the RH output signal. Refer to **FIGURE 7** for switch settings.

# FIGURE 7: OUTPUT SELECTION SWICHES



#### **HUMIDITY REVERSE ACTING OUTPUT**

The output is direct acting and can be changed to reverse acting mode. The output range stays the same but the corresponding RH value is opposite.

#### Example:

Direct Acting (DA) 0-10 V output mode, 0 V = 0% RH and 10 V = 100% RH Reverse Acting (RA) 0-10 V output mode, 0 V = 100% and 10 V = 0%

# **REVERSE ACTING OUTPUT** (Continued)

To change the transmitter to reverse acting or back to direct acting, set switch 4 to ON to put the unit in setup mode. After switch 4 is on, turning switch 2 to ON will put the unit in direct/reverse acting mode. When switch 2 is set to ON, the output can be used to show if the unit is in direct or reverse acting mode. For direct acting, the output will be 1 V for 0-5 V, 2 V for 0-10 V, and 7.2 mA for 4-20 mA. For reverse acting the output will be 4 V for 0-5 V, 8 V for 0-10 V, and 16.8 mA for 4-20 mA.

With switches 2 and 4 ON, each time switch 5 is set to ON the output will change to reverse acting or direct acting.

To reset the unit to the default setting, toggle both switches 5 and 6 ON then OFF while both switches 2 and 4 are ON.

When all calibration is completed, remember to place the switches back into the positions that correspond to the output needed as shown in **FIGURE 7**.

# **RH CALIBRATION INSTRUCTIONS**

**Note:** This is only a single point calibration. All transmitters are factory calibrated to meet/exceed published specifications. Field adjustment should not be necessary.

The dipswitch allows the user to calibrate the sensor through the software. Setting switch 4 ON will put the transmitter into setup mode allowing the increment and decrement to work.

Once in setup mode, the output will change to 50% (2.5 V for 0-5 V, 5 V for 0-10 V, 12 mA for 4-20 mA). Each increment or decrement step will cause the output to change by 0.1 V for 0-5 V, 0.2 V for 0-10 V, and 0.32 mA for 4-20 mA in setup mode. This can be used to show the user how far offset the transmitter is. To see the starting point again set switch 1 ON. This will show the 50% output again. When the unit is out of setup mode the output will go back to RH output. The maximum offset is 10%. There can be a total of 20 increments.



# **RH CALIBRATION INSTRUCTIONS** (Continued)

#### **Increment RH Output**

This will shift the RH output linearly up in 0.5% steps. Switch 4 must be set to ON first. After switch 4 is on, each time switch 5 is set ON the RH output will increase by 0.5%. The increase goes into effect each time switch 5 is set to ON.

#### **Decrement RH Output**

This will shift the RH output linearly down in 0.5% steps. Switch 4 must be set to ON first. After switch 4 is on, each time switch 6 is set ON the RH output will decrease by 0.5%. The decrease goes into effect each time switch 6 is set to ON.

#### **Reset RH Output**

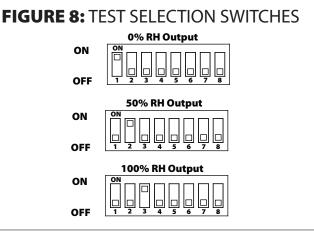
This will reset the RH output back to the original calibration. Switch 4 must be set to ON first. After switch 4 is on, toggle switches 5 and 6 ON then OFF. After 5 and 6 are OFF, slide switch 4 OFF.

When all calibration is completed, remember to place the switches back into the positions that correspond to the output needed as shown in **FIGURE 7**.

# **TEST INSTRUCTIONS**

Test mode will make the transmitter output a fixed 0%, 50%, or 100% value. The sensor will not affect the transmitter output. This is used for troubleshooting or testing only.

Switches 1, 2, and 3 are used for test mode. The output will be a fixed 0%, 50%, or 100% signal that corresponds to the output selected with switches 6, 7, and 8. Refer to **FIGURE 8** for switch settings.



# **RH CONVERSION FORMULAS**

	4-20 mA	0-5 VDC	0-10 VDC
Formula:	([mA signal] -4) / 0.16 = percent RH	[VDC signal] / 0.05 = percent RH	[VDC signal] / 0.10 = percent RH
Example:	12 mA output signal	1.25 vdc output signal	7.50 vdc output signal
	(12 - 4) / 0.16 = 50% RH	1.25 / 0.05 = 25% RH	7.50 / 0.10 = 75% RH

# WARRANTY

The ACI Duct Series RH sensors are covered by ACI's Five (5) Year Limited Warranty, which is located in the front of ACI'S SENSORS & TRANSMITTERS CATALOG or can be found on ACI's website: www.workaci.com.

# W.E.E.E. DIRECTIVE

At the end of their useful life the packaging and product should be disposed of via a suitable recycling centre. Do not dispose of with household waste. Do not burn.



# **PRODUCT SPECIFICATIONS**

	SENSOR SPECIFIC			
	RH Supply Voltage:		<b>4-20 mA:</b> 250 Ω Load: 15 - 40 VDC / 18 - 28 VAC   <b>500</b> Ω Load: 18 - 40 VDC / 18 - 28 VAC	
	(Reverse Polarity Protected)		<b>0-5 VDC:</b> 12 - 40 VDC / 18 - 28 VAC   <b>0-10 VDC:</b> 18 - 40 VDC / 18 - 28 VAC	
S	RH Supply Current (VA):		Voltage Output: 8 mA max (0.32 VA)   Current Output: 24 mA max (0.83 VA)	
ō			<b>4-20 mA:</b> 700 Ω maximum   <b>0-5 VDC or 0-10 VDC:</b> 4K Ω Minimum	
Ē	RH Output Signal:		<b>2-wire:</b> 4 - 20 mA (Default)   <b>3-wire:</b> 0-5 or 0-10 VDC and 4 - 20 mA (Field Selectable)	
U	RH Accuracy @ 77°F (25°C):		+/- 1% over 20% RH Range between 20 to 90%   +/- 2%, 3%, or 5% from 10 to 95%	
E	RH Measurement Range:		0-100%	
ШШ	Operating RH Range:		0 to 95% RH, non-condensing (Conformally Coated PCB's)	
L S	Operating Temperature Range:		-40 to 140 °F (-40 to 60 °C)	
≥	Storage Temperature Range:		-40 to 149 °F (-40 to 65 °C)	
ā			Less than 2% drift / 5 years   0.5% RH   0.1% RH	
Σ	RH Stability   Repeatability   Sensitivity: RH Response Time (T63):		20 Seconds Typical	
Ð				
ш	RH Sensor Type: RH Transmitter Stabilization Time:		Capacitive with Hydrophobic Filter	
2		•	30 Minutes (Recommended time before doing accuracy verification)	
<b>V</b>	RH Connections   Wire Size:		Screw Terminal Blocks (Polarity Sensitive)   16 (1.31 mm <sup>2</sup> ) to 26 AWG (0.129 mm <sup>2</sup> )	
Ξ	RH Terminal Block Torque Rating:		4.43 to 5.31 lb-in (0.5 to 0.6 Nm)	
~	Enclosure Specifications (Flammal	bility,	<b>"-4X" Enclosure:</b> Polystyrene Plastic, UL94-V2, NEMA 4X (IP 66)	
	Temperature, NEMA/IP Rating):		<b>"-EH" Enclosure:</b> ABS Plastic with UV Protectant, UL94-VO	
	Sensing Tube Material   Filter Material:		"-EH" Enclosure: 304 Series Stainless Steel   304 Series Stainless Steel	
			"-4X" Enclosure: Schedule 40 PVC (Wh	ite)   Slotted PVC without filter
	SENSOR NON-SPECIFIC			
	Lead Wire Length	14" (35	5.6 cm)   22 AWG (0.65 mm)	
F	Insulation Rating	Etched Teflon (PTFE) Colored Leads   Mil Spec 1678/4 Type E		
Z	THERMISTOR	1		
2	Sensor Output @ 25 °C (77 °F):	A/1.8	<b>K:</b> 1.8 KΩ nominal (Red/Yellow)	<b>A/CSI:</b> 10 KΩ nominal (Green/Yellow)
5	(Lead Wire Colors)	A/3K:	3 KΩ nominal (White/Brown)	<b>A/10KS:</b> 10 KΩ nominal (White/Blue)
9		A/AN	<b>(Type III):</b> 10 KΩ nominal (White/White)	<b>A/10K-E1:</b> 10 KΩ nominal (Gray/Orange)
N N		A/AN	- <b>BC:</b> 5.238 KΩ nominal (White/Yellow)	<b>A/20K:</b> 20 KΩ nominal (Brown/Blue)
0		A/CP	<b>(Type II):</b> 10 KΩ nominal (White/Green)	<b>A/100KS:</b> 100 KΩ nominal (Black/Yellow)
A	Accuracy @ 0-70 °C (32 - 158 °F): A/1.8		<b>K Series:</b> +/- 0.5 ℃ @ 25 ℃ (77 °F)	<b>A/10K-E1 Series:</b> +/- 0.3 °C (+/- 0.54 °F)
ΗË			and (+/-1.0 °C) (+/-1.8 °F)	<b>All Else:</b> +/- 0.2 °C (+/- 0.36 °F)
J	PLATINUM			
ЪШ	Sensor Output @ 0 °C (32 °F):	A/100	<b>:</b> 100 Ω nominal	<b>Α/1Κ:</b> 1 KΩ nominal
S S	Accuracy:	+/- 0.06% Class A (Tolerance Formula: +/- °C =		0.15 °C + (0.002 *  t ))
ENSOR		where $ t $ is the absolute value of Temperature above or below 0 °C in °C)		
Z		@ -40	°C (-40 °F): +/- 0.23°C (+/- 0.414°F)	@ 60 °C (140 °F): +/- 0.27 °C (+/- 0.49 °F)
SE		@0°0	<b>: (32 °F):</b> +/- 0.15 °C (+/- 0.27 °F)	
КШ	NICKEL			
5	Sensor Output @ 21.1 °C (70 °F):	1 KΩ r	nominal (Red/Red)	
E S	Accuracy:		° <b>C (-40 °F):</b> +/- 1.52 °C (+/- 2.73 °F)	@ 21.1 °C (70 °F): +/- 0.17 °C (+/- 0.34 °F)
Ü		-	<b>C (32 °F):</b> +/- 0.4 °C (+/- 0.72 °F)	@ 54.4 °C (130 °F): +/-0.56 °C (+/-1.00°F)
Σ	BALCO			
Ë	Sensor Output @ 21.1 °C (70 °F):	1 KΩ r	nominal (Orange/Yellow)	
	Accuracy:		<b>1 °C (70 °F):</b> +/- 1%	



# TROUBLESHOOTING

HUMIDITY READING PROBLEM	SOLUTION(S)	
No Reading	• Check that you have the correct supply voltage at the power terminal blocks.	
	Check that wiring configurations and all DIP switch settings are as in	
	FIGURE 5 and 7.	
	Verify that the terminal screws are all connected tightly and that all	
	of the wires are firmly in place.	
Erratic readings	Verify that all of the wires are terminated properly.	
	Make sure that there is no condensation on the board.	
	Check that the input power is clean. In areas of high RF interference	
	or noise, shielded cable may be necessary to stabilize signal.	
Inaccurate readings	Verify proper mounting location to confirm no external factors (see	
	mounting locations above).	
	• Check the output (voltage or current) against a highly accurate	
	recently calibrated secondary reference. Measue RH at the location of	
	the sensor using the secondary reference, then calculate the RH	
	percentage using the <b>RH CONVERSION FORMULAS</b> (p. 5). Compare	
	the calculated output to reference.	
	• If the sensor is brand new, leave the sensor powered for at least 30	
	minutes to stabilize.	
	If you suspect that the transmitter is not reading within the specified	
	tolerance, please contact ACI for further assistance.	
TEMPERATURE (Optional) PROBLEM	SOLUTION(S)	
Sensor reading is incorrect	Verify sensor wiring to controller is not damaged and has continuity	
	<ul> <li>Verify sensor or wires are not shorted together</li> </ul>	
	Verify controller is setup for correct sensor curve	
	• Disconnect sensor wires, and take a resistance (ohm) reading with a	
	multimeter	
	• Compare the resistance reading to the Temperature Vs Resistance	
	Curves online: http://www.workaci.com/content/thermistor-curves-0	
	Verify proper mounting location to confirm no external factors	
Sensor reads infinity/very high resistance	Sensor or wires are open	
Sensor reads low resistance	Sensor or wires are shorted together	



